

Discrete Symmetry Reduction

Domenico Lippolis

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Chaos Course 2022

Lorenz system

- Climate model

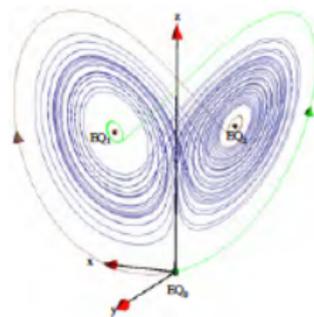
$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= \rho x - y - xz \\ \dot{z} &= xy - bz\end{aligned}\tag{1}$$

Lorenz system

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$$\begin{aligned}\dot{x} &= \sigma(y - x) \\ \dot{y} &= \rho x - y - xz \\ \dot{z} &= xy - bz\end{aligned}\tag{1}$$

- gives rise to a double-lobed chaotic attractor ($\sigma = 10, b = 8/3, \rho = 28$)



Lorenz system

- As the shape of the attractor suggests, the system is equivariant under the \mathbf{Z}_2 symmetry (π -rotation about the z -axis)

$$r(x, y, z) = (-x, -y, z) \quad (2)$$

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- Here $g(x, y, z) = r(x, y, z)$, and

$$v(g \mathbf{x}) = \begin{array}{l} \sigma(x - y) \\ -\rho x + y + xz \\ xy - bz \end{array} = g v(\mathbf{x}) \quad (4)$$

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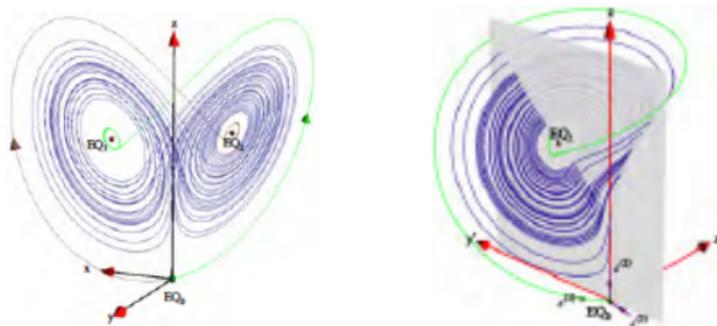
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- Then equivariance follows from $f^t(\mathbf{x}) = \mathbf{x}_0 + \int_0^t d\tau v[\mathbf{x}(\tau)]$

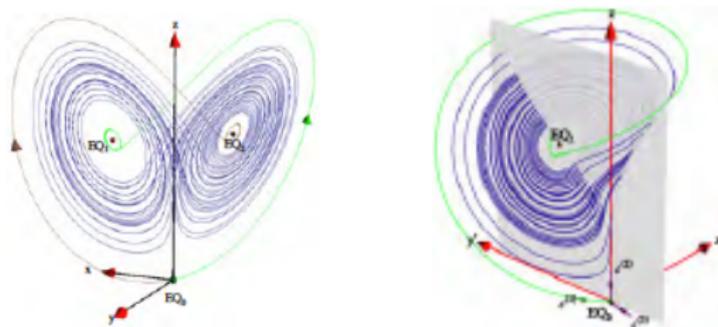
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- given a Poincaré section parallel to the z -axis, the fundamental domain \hat{M} is the half-space between the viewer and the section. Then the full flow is captured by reinjecting back into \hat{M} every trajectory that exits it, by a π -rotation about the z -axis. But how to realize that?

Lorenz system - symmetry reduction

- Rewrite the Lorenz system in cylindrical coordinates (R, θ, z) :

$$\begin{aligned}\dot{R} &= \frac{R}{2} [-\sigma - 1 + (\sigma + \rho - z) \sin 2\theta + (1 - \sigma) \cos 2\theta] \\ \dot{\theta} &= \frac{1}{2} [-\sigma + \rho - z + (\sigma - 1) \sin 2\theta + (\sigma + \rho - z) \cos 2\theta] \\ \dot{z} &= -bz + \frac{R^2}{2} \sin 2\theta\end{aligned}\tag{5}$$

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- Notably, everything depends on 2θ and not just θ . We have

$$R = \sqrt{x^2 + y^2} = \sqrt{(-x)^2 + (-y)^2}\tag{6}$$

$$\sin 2\theta = 2 \cos \theta \sin \theta = 2 \frac{x}{R} \frac{y}{R} = 2 \frac{-x}{R} \frac{-y}{R}\tag{7}$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta = \left(\frac{x}{R}\right)^2 - \left(\frac{y}{R}\right)^2 = \left(\frac{-x}{R}\right)^2 - \left(\frac{-y}{R}\right)^2\tag{8}$$

Lorenz system - symmetry reduction

- we can infer that the coordinates (R, θ, z) quotient the \mathbf{Z}_2 symmetry out of the Lorenz flow, that is

$$f^t [r(R, \theta, z)] = r (f^t [R, \theta, z]) = f^t(R, \theta, z) \quad (9)$$

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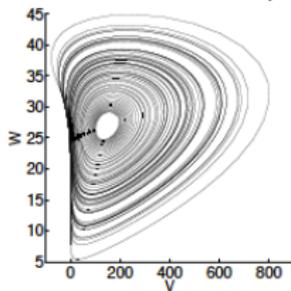
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- That's no reduction to the fundamental domain, yet. But due to the 2θ dependence we can now guess a set of coordinates

$$(V, W, z) = (R \cos 2\theta, R \sin 2\theta, z) = \left(\frac{x^2 - y^2}{R}, \frac{2xy}{R}, z \right) \quad (10)$$

that will do the job (*cf.* exercise 11.5 chaosbook)



Van der Pol oscillator

- One doesn't need chaos to reduce symmetries. Consider the nonlinearly damped oscillator

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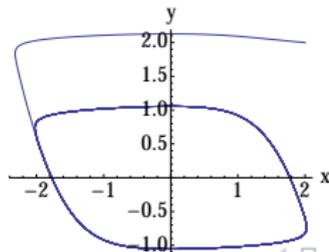
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- The dynamics quickly ($\mu = 3$) converges to a limit cycle



Van der Pol oscillator- symmetry reduction

- the Van der Pol oscillator is \mathbf{Z}_2 -symmetric (or equivariant):

$$v[r(x, y, z)] = \begin{bmatrix} \mu \left(-x + \frac{1}{3}x^3 + y \right) \\ \frac{1}{\mu}(-x) \end{bmatrix} = -v(x, y, z) \quad (13)$$

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- in polar coordinates

$$\begin{aligned} \dot{R} &= \frac{1}{R} \left[\mu R^2 \cos^2 \theta - \frac{\mu}{3} R^4 \cos^4 \theta + \left(\frac{1}{\mu} - \mu \right) R^2 \sin 2\theta \right] \\ \dot{\theta} &= \frac{1}{1 + \frac{\sin^2 \theta}{\cos^2 \theta}} \left[\frac{1}{\mu} - \frac{\mu}{\cos^2 \theta} \left(\frac{1}{2} \sin 2\theta \left(1 - \frac{1}{3} \cos^2 \theta \right) - \sin^2 \theta \right) \right] \end{aligned} \quad (14)$$

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- Again, that depends on 2θ and we can make the same change of coordinates as for the Lorenz system.

Exercise: plot the symmetry-reduced Van der Pol limit cycle

Transfer operator

- Alternatively to ODEs, one can follow as swarm of trajectories, obeying the Liouville equation

$$\partial_t \rho(x, t) + \nabla \cdot [\rho(x, t) v(x)] = 0 \quad (15)$$

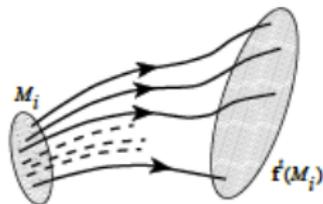
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$$\partial_t \rho(x, t) + \nabla \cdot [\rho(x, t) v(x)] = 0 \quad (15)$$

- or, equivalently, $\rho(x, t)$ is transported by the flow $f^t(x)$ via the Perron-Frobenius operator

$$\rho(x, t) = (\mathcal{L}^t \circ \rho)(x) = \int dx_0 \delta(x - f^t(x_0)) \rho(x_0, 0) \quad (16)$$



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$$\mathcal{L}(y, x) = \int dx \delta(y - f(x)) \circ \quad (18)$$

- constraining densities on the orbit $y = f(x)$ so that for a g -symmetric flow

$$\mathcal{L}(gy, gx) = \int dgx \delta(gy - f(gx)) \circ = \int dgx \delta(g[y - f(x)]) \circ \quad (19)$$

still constrains the dynamics on $y = f(x)$.

Transfer operator

- Moreover

$$\begin{aligned}\mathcal{L}(gy, gx) \rho(x) &= \int dgx \delta(gy - f(gx)) \rho(x) \\ &= \int_{g(\mathbb{R})} du \delta(gy - f(u)) \rho(f^{-1}(u)) \\ &= \sum \rho(g^{-1}f^{-1}(gy)) [g^{-1}f^{-1}(gy)]' \\ &= \sum_{y=f^{-1}(x)} \frac{\rho(f^{-1}(y))}{|f'(y)|} = \mathcal{L}(y, x) \rho(x) \quad (20)\end{aligned}$$

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 \end{aligned}$$

- Thus the symmetry condition $f(x) = g^{-1}f(gx)$ is equivalent to $\mathcal{L}(gy, gx) = \mathcal{L}(y, x)$

Example

- Consider a \mathbf{Z}_2 symmetry operation C for a 2D map $x_{n+1} = f(x_n)$, such that

$$f(Cx) = Cf(x), \quad C = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \quad (21)$$

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- The phase space can be decomposed into symmetric and antisymmetric spaces by means of the projectors

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- Applied to the transfer operator to obtain

$$\mathcal{L}_{A_1} = P_{A_1} \mathcal{L}(y, x) = \frac{1}{2} [\mathcal{L}(y, x) + \mathcal{L}(-y, x)] \quad (23)$$

$$\mathcal{L}_{A_2} = P_{A_2} \mathcal{L}(y, x) = \frac{1}{2} [\mathcal{L}(y, x) - \mathcal{L}(-y, x)] \quad (24)$$

Transfer operator decomposition

- In general, consider the projector

$$P_\alpha = \frac{d_\alpha}{|G|} \sum_h \chi_\alpha(h) h^{-1} \quad (25)$$

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- The P_α 's split the transfer operator into a sum of irreducible space contributions, each

$$\mathcal{L}_{A_\alpha}(y, x) = \frac{d_\alpha}{|G|} \sum_{h \in G} \chi_\alpha(h) \mathcal{L}(h^{-1}y, x) \quad (27)$$

Transfer operator decomposition

- In the example, the \mathbf{Z}_2 group has two irreps, such that

$$\begin{aligned}\chi_1(e) &= 1, & \chi_1(C) &= 1 \\ \chi_2(e) &= 1, & \chi_2(C) &= -1\end{aligned}$$

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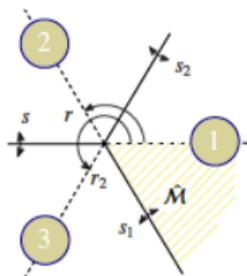
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- Contributions to the trace come from periodic orbits

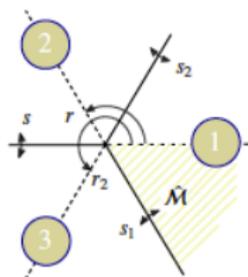
Three-disk scatterer



- Symmetry group is D_3 , dihedral

$$D_3 = \{e, r, r_2, s, s_1, s_2\} \quad (30)$$

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- in matrix representation

$$e = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad r = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{pmatrix}, \quad r_2 = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{pmatrix}$$

$$s = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad s_1 = \begin{pmatrix} -1/2 & \sqrt{3}/2 \\ \sqrt{3}/2 & 1/2 \end{pmatrix}, \quad s_2 = \begin{pmatrix} -1/2 & -\sqrt{3}/2 \\ -\sqrt{3}/2 & 1/2 \end{pmatrix}$$

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- D_3 is *not* Abelian, for example

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- multiplication table

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r	r	r_2	1	s_2	s	s_1
r_2	r_2	1	r	s_1	s_2	s
s	s	s_1	s_2	1	r	r_2
s_1	s_1	s_2	s	r_2	1	r
s_2	s_2	s	s_1	r	r_2	1

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s_1	s_1	s_2	s	r_2	1	r
s_2	s_2	s	s_1	r	r_2	1

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- ...And three classes

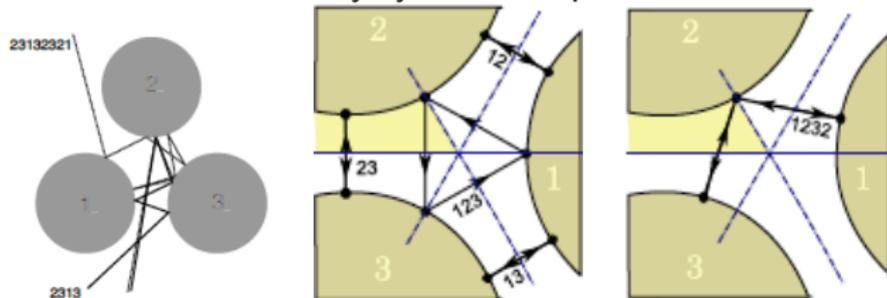
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Cycles and their symmetries

- The pinball is an *open* system, so everything escapes eventually. The transient chaotic dynamics is nailed by the trapped orbits.

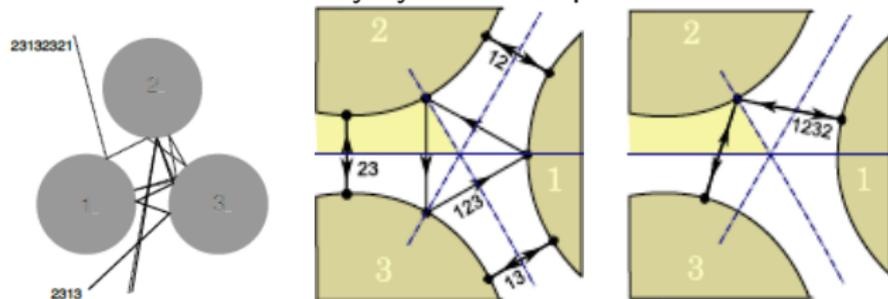
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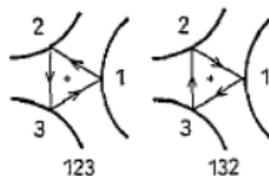
- Then symmetry operations can be applied directly to symbols, e.g.

$$r(\overline{12}) = \overline{23}, \quad r(\overline{23}) = \overline{31}, \quad r(\overline{31}) = \overline{12} \quad (34)$$

Cycles and their symmetries

- More examples:

$$s_1(\overline{123}) = \overline{132} \quad (35)$$

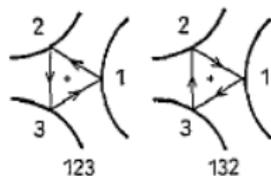


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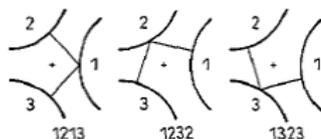
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- cycles $\overline{1213}$, $\overline{1232}$ and $\overline{1323}$ are invariant under D_1 (flips), e.g.

$$s_1(\overline{1213}) = \overline{1312} = \overline{1213} \quad (36)$$

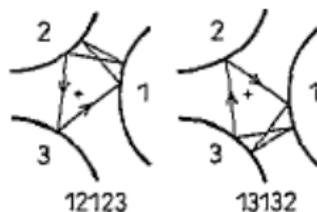


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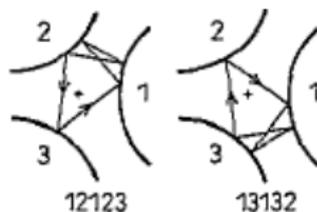
- six-degenerate five-cycle $\overline{12123}$:



$$s(\overline{12123}) = \overline{13132} \quad (38)$$

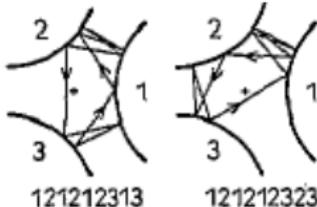
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- Besides D_3 -symmetries, pinball has time-reversal- :



$$T(\overline{121212313}) = \overline{121212323} \quad (39)$$

Fundamental domain

- Reduce three symbols 123 to two: 0 (backward) and 1 (forward)

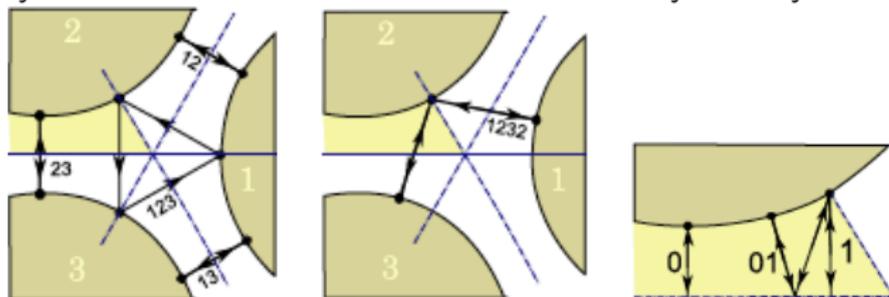


Fundamental domain

- Reduce three symbols 123 to two: 0 (backward) and 1 (forward)



- Restrict the dynamics to one disk + reflection off the symmetry axes:

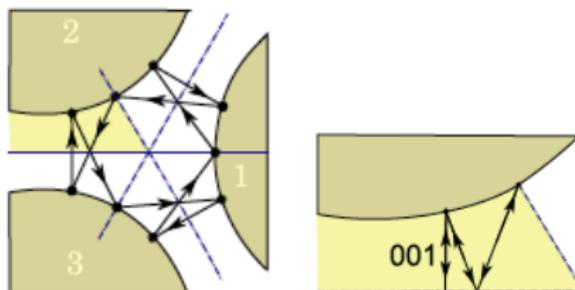


$$\overline{23} \rightarrow \overline{0}, \overline{123} \rightarrow \overline{1}, \overline{1232} \rightarrow \overline{01} \quad (40)$$

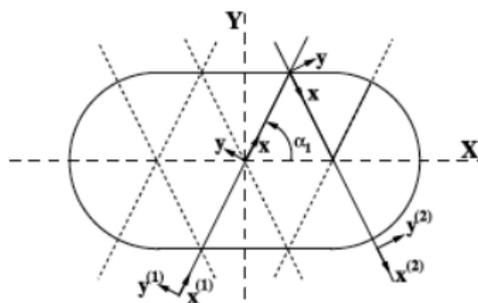
Fundamental domain

- Time-reversal nine-cycle

$$\overline{121212323} \equiv \overline{121212313} \rightarrow \overline{001} \quad (41)$$



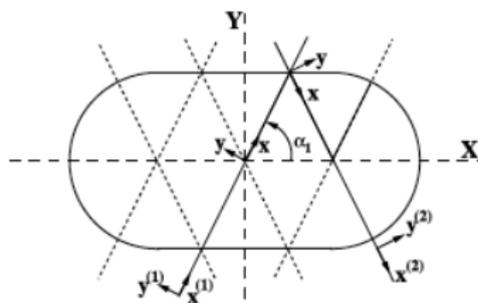
Bunimovich stadium



- C_{2v} symmetry group

$$C_{2v} = \{e, s_x, s_y, C_2\}$$

Bunimovich stadium

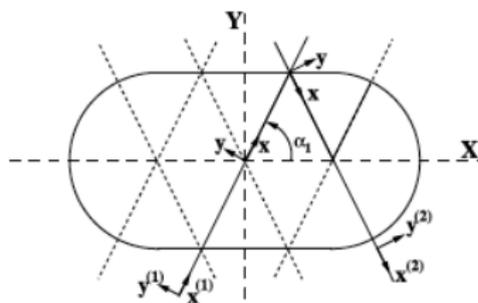


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Bunimovich stadium

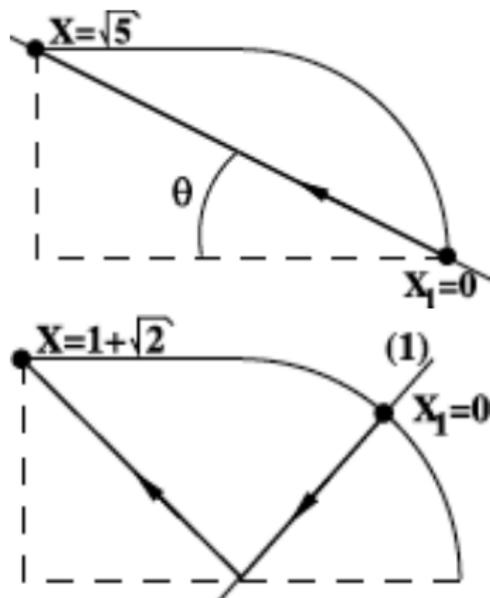
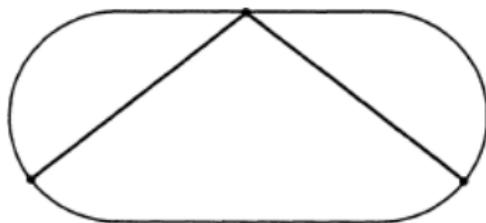
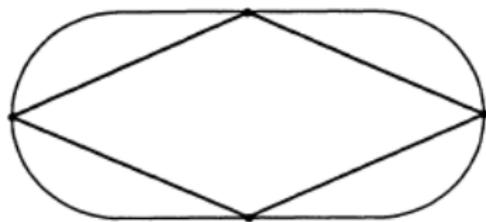


- C_{2v} symmetry group

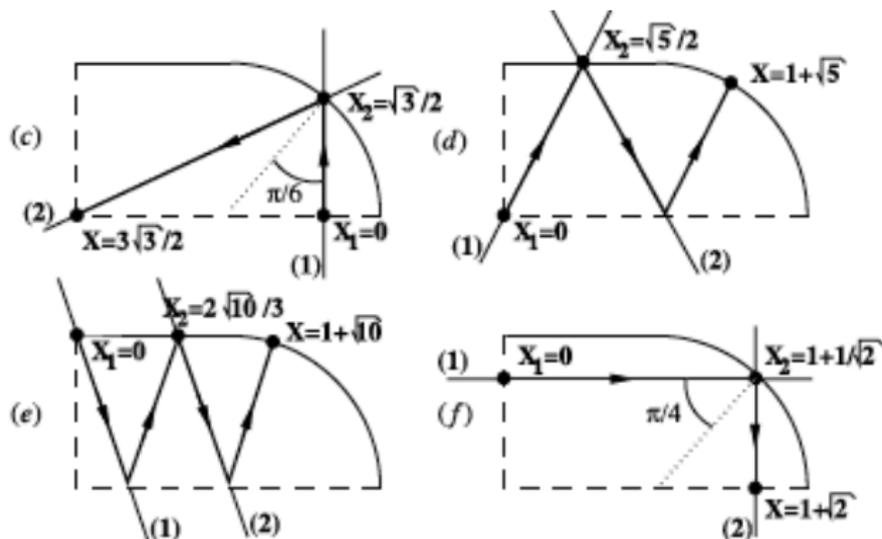
$$C_{2v} = \{e, s_x, s_y, C_2\}$$

- s_x, s_y flips around x -, y -axes
- C_2 rotation by π

Desymmetrization

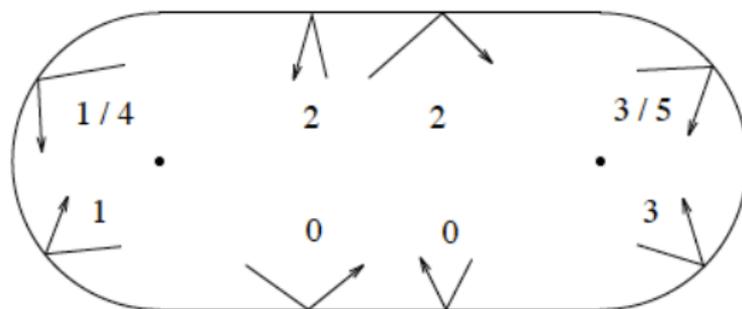


Desymmetrization

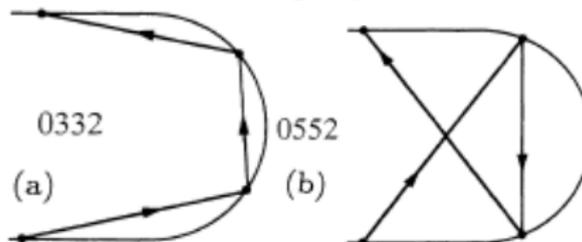


E G Vergini and G G Carlo, J. Phys. A: Math. Gen. **33**, 4717 (2000)

Symbolic dynamics

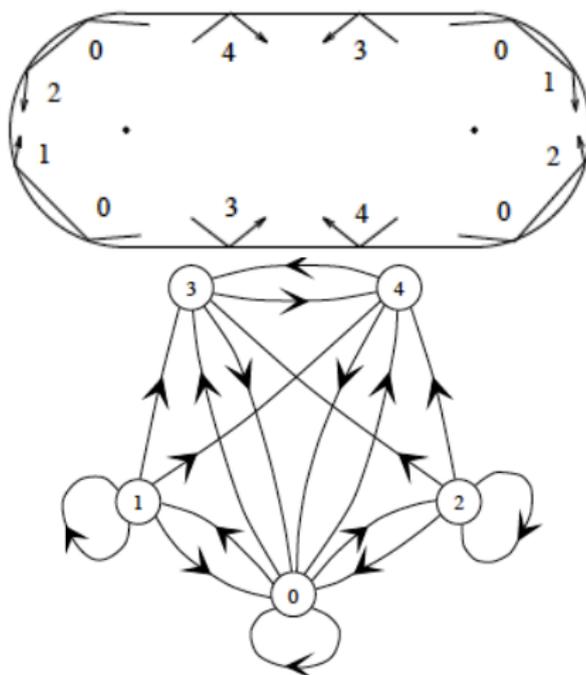


- six symbols to avoid directional ambiguity



K T Hansen and P Cvitanović, *chao-dyn/9502005* (1995); O. Biham and M Kvale, *Phys. Rev. A* **46**, 6334 (1992)

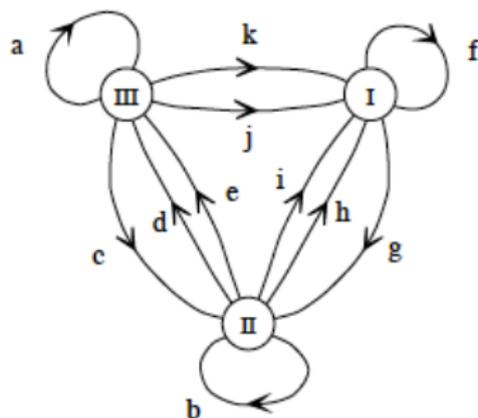
Five-symbol dynamics



Symmetry-reduced symbolic dynamics

s_t	$\sigma_{t-1}\sigma_t$	$\sigma_{t-n-1}0^n\sigma_t$
a	11	
	22	
b	00	
c	10	
	20	
d	01	$_10^n1_$
	01	$_40^n1_$
	02	$_20^n2_$
e	02	$_30^n2_$
	01	$_20^n1_$
	01	$_30^n1_$
f	02	$_10^n2_$
	02	$_40^n2_$
f	34	
	43	

s_t	$\sigma_{t-1}\sigma_t$	$\sigma_{t-n-1}0^n\sigma_t$
g	30	
	40	
h	03	$_20^n3_$
	03	$_30^n3_$
	04	$_10^n4_$
	04	$_40^n4_$
i	03	$_10^n3_$
	03	$_40^n3_$
	04	$_20^n4_$
	04	$_30^n4_$
j	23	
	14	
k	24	
	13	



Coupled Map Lattices

- Dynamical systems with discrete space and time and continuous state variables

$$\Phi_{n+1}^{(i)} = (1 - a)f\left(\Phi_n^{(i)}\right) + \frac{a}{2}\left[g\left(\Phi_n^{(i+1)}\right) + g\left(\Phi_n^{(i-1)}\right)\right] \quad (42)$$

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- It becomes a system of N coupled maps, e.g. ($N = 2$, set $f = g$)

$$x_{n+1} = (1 - a)f(x_n) + af(y_n) \quad (43)$$

$$y_{n+1} = (1 - a)f(y_n) + af(x_n) \quad (44)$$

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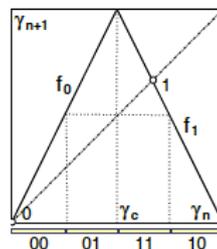
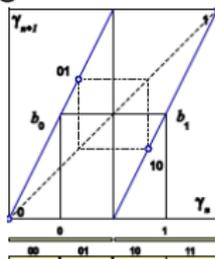
- $a = 0$ yields uncoupled dynamics, that is every lattice site follows its own independent dynamics given by f

$$x_{n+1} = f(x_n) \quad (45)$$

$$y_{n+1} = f(y_n) \quad (46)$$

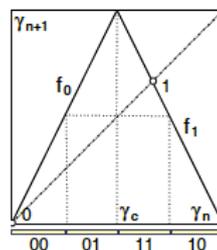
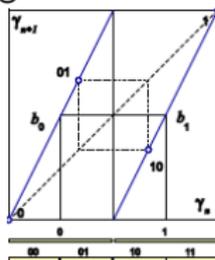
Coupled Map Lattices

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Coupled Map Lattices

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- Take for example the periodic points of period $n_p = 2$: the single map has

$$\begin{array}{cccc} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{array} \quad (47)$$

Coupled Map Lattices

Then the two-dimensional map has $4^2 = 16$ periodic points classified as

- six prime orbits

$$\begin{array}{cccccc} 00 & & 00 & & 10 & & 01 & & 00 & & 01 \\ 01 & , & 11 & , & 11 & , & 10 & , & 10 & , & 11 \end{array} \quad (48)$$

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- and four period-one repeated orbits

$$\begin{array}{cccc} 00 & 01 & 10 & 11 \\ 00 & , & 01 & , & 10 & , & 11 \end{array} \quad (50)$$

Coupled Map Lattices - symmetry reduction

- A symmetrically coupled lattice of N spatial sites has symmetry group D_N of order $2N$ (spatial cyclic permutation + reflections)

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- one boundary orbit ($x = y$) originally of period two

$$\begin{array}{c} 00 \\ 11 \end{array} \quad (52)$$

Coupled Map Lattices - symmetry reduction

- and three symmetric orbits of original period four

$$\begin{array}{ccc} 00 & 01 & 10 \\ 01 & 01 & 11 \\ 00 & ' & 10 & ' & 01 \\ 10 & & 10 & & 11 \end{array} \quad (53)$$

Coupled Map Lattices - symmetry reduction

- and three symmetric orbits of original period four

$$\begin{array}{ccc}
 00 & 01 & 10 \\
 01 & 01 & 11 \\
 00 & ' & 10 & ' & 01 \\
 10 & & 10 & & 11
 \end{array} \tag{53}$$

- Applying the flip $s : (x, y) \rightarrow (y, x)$, the orbits of the last group are all copies of the orbits of the first group, or repeated orbits, and we are left with

$$\begin{array}{ccc}
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 \end{array} \tag{54}$$

as prime cycles in the fundamental domain $x \geq y$

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- Exercise: desymmetrize period-two orbits for lattices with $N = 3$ (hence for D_3 symmetry group)